

THERMAL ENERGY AND OTHER TYPES OF INTERNAL ENERGY

1] FRICTION AND THERMAL ENERGY

- Until this section, *all mechanics is based on the model of object as a single material point*. In reality, the material objects are constituted by *atoms (or molecules)* which "**interact between them and move inside the object**" and this means some "**energy inside the object**". Atoms (or molecules) are **strongly bound to each other** inside a **solid**, **slightly bound between them** inside a **liquid** and they are **free** (not bound) inside a **gaz**. Also, no matter what is the **physical state(solid, liquid or gas)** of an object, its *atoms (or molecules)* are in a **continuous random motion**. This type of motion is characterized by an **average speed** of moving particles and this means a kind of **kinetic energy inside the object**. The **temperature** of the object is a macroscopic parameter related to the **average kinetic energy** of atoms (or molecules) inside it. When this type of kinetic energy increases, the *temperature of object increases and vice versa*. **Thermal energy** " E_{th} " is the amount of energy related to the *random motion* of microscopic particles **inside an object**. Next, one derives the *principle of energy conservation* for a system constituted by objects with microscopic structure, i.e. a system that contains **thermal energy**.

-One may easily realise (*just by rubbing hands*) that two bodies that rub on each other *produce heat*. This **heat increases** the **thermal energy** E_{th} of the two bodies (*hands get warm*). Precise measurements show that the *increase of thermal energy of the two bodies* is equal to the **magnitude** of work done by friction.

$$\Delta E_{th}(> 0) = -W_f = -(-f_k * d) = f_k * d \tag{1}$$

As the kinetic **friction** is one of external **forces** acting on the **system**, one may separate the work by friction at expression of mechanical energy conservation in Fig. 1 principle and get

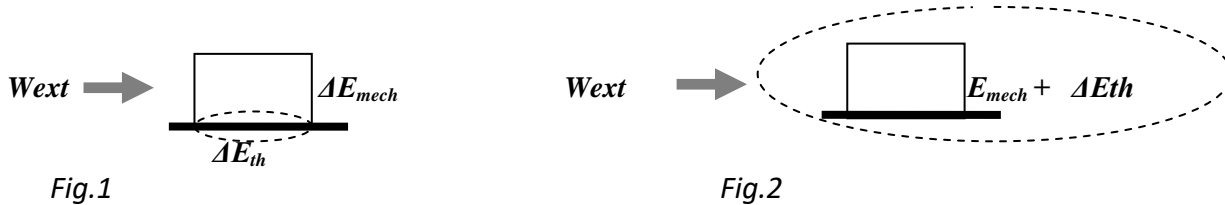
$$W_{ext_net} = W_{ext} + W_f = \Delta E_{mech} \tag{2}$$

Then, $W_{ext} = \Delta E_{mech} - W_f = \Delta E_{mech} + \Delta E_{th}$ and rewrite the principle of energy conservation as

$$W_{ext} = \Delta E_{mech} + \Delta E_{th} \tag{3}$$

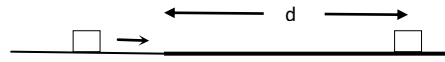
-Note that W_{ext} in this expression does not include the work by friction. So, the **external work without friction work goes** for the **change of total mechanic energy** of the system and the **change** of the **thermal energies** of the system ΔE_{th_sys} and that of the external objects ΔE_{th_obj} in contact with system parts (fig.1).

$$\Delta E_{th} = \Delta E_{th_sys} + \Delta E_{th_obj} \tag{4}$$



One may include into system the "*adjacent objects affected by friction*" and consider the friction as an **internal but non-conservative** force of system (fig.2). Then, the expression (3) would tell that net external work (**friction work is not any more external**) goes to change the mechanical and thermal energies of the system.

Example: A block with mass $m=10\text{kg}$ that starts sliding at speed $v = 5\text{m/s}$ on a horizontal plane stops at a distance “ d ” due to friction force $f_k = 5\text{N}$ applied on it by plan.



a) Find the *change of thermal energy* ΔE_{th} of *block - plan set* and b) Find “ d ”

If one sees the words *temperature or thermal*, one may **exclude the work by friction from the external work and refer to the principle energy in form (3).**

By excluding the friction from external forces, in this example one get $W_{ext} = 0$ and the relation (3) gives

$$\Delta E_{mech} + \Delta E_{th} = W_{ext} = 0 \quad \text{or} \quad \Delta(U_G+K) + \Delta E_{th} = 0 \quad \text{or} \quad \Delta U_G + \Delta K + \Delta E_{th} = 0 \quad \text{and} \quad \Delta K + \Delta E_{th} = 0$$

because $\Delta U_G = 0$ (same height) So, $(0 - 10 \cdot 5^2 / 2) + \Delta E_{th} = 0$ and a) $\Delta E_{th} = E_{th2} - E_{th1} = 125 \text{ J}$

b) As, $\Delta E_{th} = |W_f| = f_k \cdot d$ it comes out that $125\text{J} = 5\text{N} \cdot d$ and $d = 25\text{m}$

Note: The models that take into account the changes in internal energy of objects are used mainly in the frame of **thermodynamics**. In this course, we refer *mainly* to a system where **friction is an external force** (W_f is an external work) and use the principle of mechanic energy conservation for a **material point model**

$$W_{ext_net} = \Delta E_{mech} = \Delta K + \Delta U \tag{5}$$

If requested, one calculates the *total amount of thermal energy* produced from the work by friction as $\Delta E_{th} = -W_f$.

Important: The experiments show that **K** and **U** can **transform completely** into each other **or** into E_{th} but E_{th} cannot transform **completely** into **K** or **U**. **A disorganized motion cannot be converted naturally (by itself) into an oriented motion.** Ex: A hot block at rest cannot start moving along one direction just because its temperature decreases. That’s why the *thermal energy is not considered* as a pure mechanical energy. Also, one measures the *thermal energy (or heat)* by a particular unit “calorie” ($1 \text{ cal} = 4.186 \text{ J}$)

2] OTHER TYPES OF INTERNAL ENERGY

- Let’s consider an **exothermic chemical reaction** inside a sealed container. The molecules “**A**” interact with molecules “**B**” at room **temperature** and produce molecules **A-B**. Simultaneously, the chemical reaction releases heat which increases the **temperature** ($\Delta E_{th} > 0$) in container. If the **thermal energy** of particles in sample increases too much, it may be produced an **explosion and pieces of sample get out container at high speed (i.e. they get kinetic and gravitational energy changes)**. As the sample of molecules (A, B and A-B) is an **isolated** system ($W_{ext} = 0$), the principle of energy conservation (3) would tell that $\Delta E_{mech} + \Delta E_{th} = 0$. But *the experiment shows that* $\Delta E_{mech} > 0$ and $\Delta E_{th} > 0$, which means that $\Delta E_{mech} + \Delta E_{th} > 0$. One can avoid this contradiction by taking into account that there is a **molecular energy inside each of the molecules** and label the total amount of this type of energy over all molecules in container as “ E_{mol} ”. This energy remains **constant** as long as there is **no chemical reaction, but** it changes when a chemical reaction happens. So, the total energy of all molecules in container is

$$E_{tot} = E_{mech} + E_{th} + E_{mol} \tag{6}$$

Next, the principle of energy conservation for an isolated system would be written $\Delta E_{tot} = W_{ext} = 0$

$$\Delta E_{mech} + \Delta E_{th} + \Delta E_{mol} = 0 \quad \text{and} \quad \Delta E_{mech} + \Delta E_{th} = -\Delta E_{mol} > 0 \quad \text{i.e.} \quad \Delta E_{mol} = E_{mol-2} - E_{mol-1} < 0$$

This means that, during an *exothermic chemical reaction*, the amount of energy *lost* ($\Delta E_{mol} < 0$) by the *internal molecular energy of the system* goes to increase its *mechanical and thermal energy*.

-Inside a battery, the *molecular energy* get transformed (*via a chemical reaction*) into *electrical energy* E_{elect} which is another type of *internal energy*. There exist a set of other *internal energies* (E_{struct} in a solid or liquid structure, E_{at} - atomic energy inside the atoms, E_{nucl} - nuclear energy inside the nuclei and E_{rad} - radiation energy) which cannot transform *completely* and *naturally* into *pure mechanic energy* (K or U). So, they are all *non-mechanical* forms of energy. If one group all them into a single term E_{int} (*internal energy*) without including E_{th} , one gets

$$E_{int} = E_{electr} + E_{struct} + E_{mol} + E_{at} + E_{nucl} + E_{rad} \quad (7)$$

and the *total energy* of an object can be expressed as $E_{tot} = E_{mech} + E_{th} + E_{int}$ (8)

Note: In mechanics, one prefers to distinguish the term E_{th} from other terms of E_{int} .

3] GENERAL PRINCIPLE OF ENERGY CONSERVATION

The results of *multiple experiments* confirm the following:

- If one includes *inside a system all the objects that may interact to each other*, one creates an *isolated system*. The *total energy* of an *isolated system* *remains constant in time* i.e.

$$\Delta E_{tot} = \Delta E_{mec} + \Delta E_{th} + \Delta E_{int} = 0 \quad (9)$$

Note: This does not exclude motion and energetic exchanges inside the system; but if they happen, the amount of energy transformed from one form to another form is such that the total energy remains constant.

- If the system is *not isolated* the *amount of energy* that it exchanges with *adjacent space regions* $E_{exchange}$,

is equal to the change of its total energy $\Delta E_{tot} = E_{tot-2} - E_{tot-1} = E_{exchange}$ (10)

If the system *exchanges only work* with *adjacent space regions*, then $E_{exchange} = W_{ext}$ (11)

and $W_{ext} = \Delta E_{mech} + \Delta E_{th} + \Delta E_{int}$ (12)

Remember:

*The total energy of system increases if $W_{ext} > 0$ and decreases if $W_{ext} < 0$.

* The work by friction is not included into W_{ext} at expressions (3, 11, 12).

*The *principle of total energy conservation* (12) transforms into form $W_{ext} = \Delta E_{mech}$ when $\Delta E_{int} = 0$.