#### 13.1 ALTERNATING CURRENT AND THE PHASOR MODEL

- If the circuit contains only DC sources, the current *flows all time in one direction*; one says that it is a **directed current (DC)**. But, in everyday activity, one deals often with *alternating currents* (**AC**) and AC sources(*wall socket, car alternators etc...*). The AC is a *current that changes its direction of flowing through circuit in time*. Even the turbines of hydro/thermo centrals that provide the electric energy used in majority of human activity operate as AC sources. In North America, the wall outlets provide an AC voltage that oscillates as a harmonic function at a " *natural* " frequency f = 60Hz (i.e.  $\omega = 2\pi f = 376.8 \text{ r/s}$ ).
- -Remember: The AC generator is a coil that rotates at a period T (or frequency f = 1/T or  $\omega = 2\pi f$ ) i.e. circular frequency  $\omega = 2\pi f$  T inside an uniform magnetic field. The direction of the inducted emf changes with time in conformity to the sign of expression  $\varepsilon = \varepsilon_0 \sin(\omega t)$ . When one switches this emf into a circuit, it provides an harmonic AC source of electricity.

In principle, an AC source is not necessarily harmonic but one may show that any AC voltage *can be* expressed as a sum of a set of harmonic AC voltages with different frequencies (for more information see Fourier transformations). However, if one says AC without additional precision, this means harmonic AC.

- In this chapter one uses the notations "i and v" to distinguish a current and a voltage that *changes* with time. The uppercase letters (like I and V) will be used only for quantities that do not change with time. In general, an AC source *provides into the circuit* a **potential difference**, commonly called

a **voltage**, which instantaneous value is given by expression

$$\upsilon = \upsilon_0 \sin(\omega t + \varphi_n) \tag{1}$$

The instantaneous current in circuit oscillates at same frequency; so

$$i = i_0 \sin(\omega t + \varphi_i) \tag{2}$$

 $v_o$ ,  $i_o$  are the maximum values(or amplitudes);  $\omega = 2\pi/T$  is the circular frequency;  $\varphi_v$ ,  $\varphi_i$  are the phase constants.

**Note:** The circular frequency  $\omega$  is defined by the "rotation frequency of the coil in AC generator".

- One refers to the *phasor physic's model* for the study of a parameter that oscillates in harmonic way with time, like voltage and current in a AC circuit.

The phasor itself is a virtual vector that rotates counter clockwise at **circular frequency**  $\omega = 2\pi f$  where f = 1/T is the real frequency(in hertz) of oscillations for the physical quantity under study (see fig. 1).

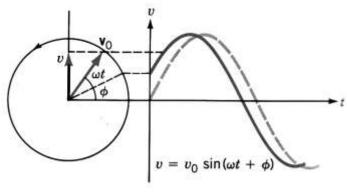


Figure 1

The "length" of the phasor vector is equal to the maximum value(ex.  $v_o$  or  $i_o$ ) of oscillating parameter and the component of phasor along the vertical axis (Oy) is equal to its instantaneous value. By using the rules of trigonometric circle, one finds out easily that:

- a) the **phase** is equal to the **angle**  $\Phi(t) = \omega t + \varphi$
- b) if one starts(t = 0) the study from a moment when the value of considered parameter is zero, then the **phase constant**  $\varphi = 0$
- c) if one starts (t = 0) the study of parameter at a moment when the variable is not zero, the **phase constant**  $\varphi \neq 0$ .

- One uses the *same* phasor diagram for different physical variables that oscillate at the same  $\omega$  and this allows to visualise the phase shift between different AC variables (currents and voltages) in same circuit.

The *phase shift* between *voltage and current* plays a very important role in calculations for AC circuits. As mentioned, the value of the phase constant " $\varphi$ " depends on the selection of t = 0. In a AC circuit with a resistor, an inductor and a capacitor (R,L,C set) <u>in series</u>, the current value through all elements of circuit is the same at any moment.

So, one selects t = 0 at a moment when the instantaneous current is zero and this way gets  $\varphi_i = 0$ .

Then, one can write the current as

$$i = i_0 \sin(\omega t) \tag{3}$$

and the *phase constant*  $\varphi$  of instantaneous voltage represents the *phase shift voltage – current* 

$$\upsilon = \upsilon_0 \sin(\omega t + \varphi) \tag{4}$$

**Notes**: a) One uses the notations v,  $v_R$ ,  $v_C$ ,  $v_L$  for instantaneous values of voltage across the terminals of the *source*, *resistor*, *capacitor*, *inductor* and the sign  $\bigcirc$  to show an AC source in circuit.

b) The *instantaneous* current and voltage *values* are counted on the same "Oy" axis (see fig.2).

## 13.2 RESISTOR IN AC CIRCUIT

- Let's consider the scheme in figure 2; the resistor R is connected "in series" with an *AC* source. At a moment "t", the voltage at source terminals is v(t) and the current through resistor is i(t). By applying the loop's rule, one get  $v - v_R = 0$ . So, at any moment  $v_R = v$ . As the current oscillates as  $i = i_0 \sin(\omega t)$ , the Ohm's law gives  $v_R = iR = i_0 R \sin(\omega t) = v_{0R} \sin(\omega t)$  (5)

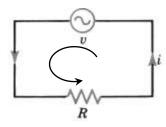


Figure 2

As  $v = v_R$ , it comes out that  $v = v_0 \sin(\omega t) = i_0 R \sin(\omega t)$  (6) Those relations show that for a **resistor**:

- The *phase shift* between *applied voltage* and *current* is zero ( $\varphi = 0$ )

- The peak value of current is 
$$i_0 = \frac{v_{0R}}{R} = \frac{v_0}{R}$$
 (7)

**Remember**: The circular frequency " $\omega$ " of current is defined by the source and is the same as that of its voltage.

The graphs in figure 3b show the evolution of current and voltage across resistor with time and the figure 3a shows their *phasors* at a moment "t" in a *phasor diagram*. Those two presentations show that "i(t) and v(t) pass <u>simultaneously</u> through their maximal, minimal and zero values ".

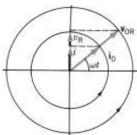
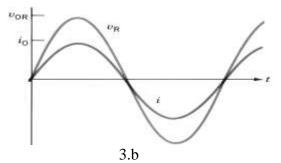


Figure 3.a



## K.Angoni, Physics Dept., Vanier College

- What is the *power dissipated as heat in resistor*? One may tent to find the average of current " *i(t)* " during one period and calculate an average power by formulae  $P = (i_{av})^2 * R$ . But the graph of current in fig.3b shows that this  $i_{av} = 0$  and one would get P = 0. Meanwhile, with the exception of only two moments,  $i^2 > 0$  and the instantaneous dissipated power in resistor is  $p(t) = i(t)^2 R > 0$  which means that the average power dissipated in resistor for one period must be positive; i.e. it cannot be zero. This is a good example which shows why each mathematical result has to be considered carefully if it does make sense or not from the physics point of view.

For this calculation, one must start from instantaneous power  $p(t) = i^2 R = i_0^2 R \sin^2(\omega t)$ (8)

Next, 
$$P_{av} = \frac{1}{T} \int_{0}^{T} p(t) dt = \frac{1}{T} \int_{0}^{T} i_{0}^{2} R \sin^{2} \omega t dt = \frac{i_{0}^{2} R}{T} \int_{0}^{T} \frac{(1 - \cos 2\omega t)}{2} dt = \frac{i_{0}^{2} R}{2T} \int_{0}^{T} dt = \frac{i_{0}^{2} R}{2T} t \Big|_{0}^{T} = \frac{i_{0}^{2} R}{2}$$
 (9)

**Notes:** a) One used trigonometric equity  $sin^2\theta = \frac{1}{2}(1 - cos2\theta)$ 

b)  $\frac{1}{T} \int \cos(2\omega t) dt = 0$  as period average for a harmonic function.

As the average of current square in a period is  $(i^2)_{av} = \frac{i_0^2}{2}$  (10) (refer to integral (9) without R) it comes out that  $P_{av} = (i^2)_{av} R$  (11)

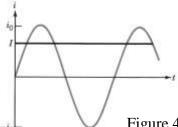
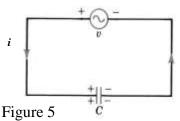


Figure 4

- One prefers to use for AC circuits similar formulas to those found for DC circuits. So, one has introduced the **root mean square** (rms) current (I in fig.4) as  $I_{rms} = \sqrt{(i^2)_{av}} = \frac{i_0}{\sqrt{2}} = 0.707i_0$  (12) Then, the average power dissipated in resistor  $P_{av}$  (mostly called  $rms\ power$ ) is  $\dot{P}_{rms} = I_{rms}^2 R$ **Root mean square (rms)** potential difference is defined as  $V_{rms} = \sqrt{(v^2)_{av}} = \frac{v_0}{\sqrt{2}} = 0.707v_0$ With this definition, one can write the Ohm's law in AC circuits as (15)

- Expressions 12-15 relate the **rms** or *effective* values of *current, voltage and power* in an AC circuit. The effective power (rms power at expression 13) is known also as heating power of AC in a circuit. This amount of power is dissipated as heat in a resistor R and it is the same as that dissipated in this resistor by a DC current with  $I=I_{rms}$ . Note that the voltage 120V provided by wall plugs in North America is a *rms voltage*; it corresponds to a AC voltage with amplitude  $v_0 = 120/0.707 = 169V$ . All devices that measure I, V in AC circuits provide approximate rms values. One must use devices labeled "TRUE RMS values" to measure AC parameters with a **good** precision. The best way to measure all characteristics of AC is by use of a scope.

### 13.3 CAPACITOR IN AC CIRCUIT



- The scheme in figure 5 shows a capacitor C connected "in series" to an AC source. Let's consider an interval  $(t_0, t)$  during which the charge q on C plates is *increasing* due to a "positive" *current in the* circuit that brings (+) charges to positive plate(see fig.5). In these

 $\frac{dq}{dt} > 0$  and  $\frac{dq}{dt} = i$ circumstances one gets (16)

Remembering that the current evolution in time is assumed with a *phase constant* zero;  $i = i_0 \sin(\omega t)$ 

one gets  $\frac{dq}{dt} = i_0 \sin \omega t$  (17) So,  $dq = i_0 \sin(\omega t) dt \rightarrow q = \int_{t_0}^{t} dq = \int_{t_0}^{t} i_0 \sin(\omega t) dt = \frac{i_0}{\omega} \int_{\omega t_0}^{\omega t} \sin x dx$ 

which gives  $q = -\frac{i_0}{\omega}\cos(\omega t) + const(t_o)$  (18) One takes  $const(t_o) = 0$  and this way gets rid of it.

So, the *evolution of charge* in capacitor is given by expression  $q = -\frac{i_0}{\omega}\cos(\omega t) \tag{19}$ 

Then, the instantaneous difference of potential across capacitor plates is

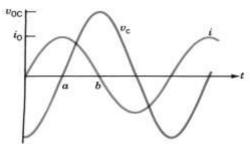
$$v_C = \frac{q}{C} = -\frac{i_0}{\omega C} \cos(\omega t) \equiv -v_{0C} \cos(\omega t)$$
 (20)

<u>Notes</u>: a) The maximum value of potential difference across capacitor plates is  $v_{0C} = i_0 \frac{1}{\omega C}$  (21)

**b)** As  $i = i_0 \sin(\omega t)$  and  $\upsilon_C = -\upsilon_{0C} \cos(\omega t) = \upsilon_{0C} \sin(\omega t - \pi/2)$ , it comes out that the *potential difference at capacitor plates* is **delayed** (or lags) by  $\pi/2$  (see fig.6a.b) with respect to *current in circuit*.

Figure 6.a

Figure 6.b



c) By applying the second rule of Kirchhoff for the loop;  $\upsilon - \upsilon_C = 0$ ; so, at each moment  $\upsilon_C = \upsilon$  (22) The difference of potential at capacitor plates is equal to source voltage at each instant. At time " t = a " (fig.6.b)  $\upsilon_C = \upsilon = 0 \Longrightarrow q = \upsilon_C *C = 0$ . During the time (a, b), the potential difference  $\upsilon_C$  (and q) of capacitor increases while its *charging rate* " dq/dt", i.e. the *current* in circuit, *decreases*. At " t = b " when the voltage  $\upsilon_c = \upsilon_{\theta C}$ , the current in circuit becomes zero. For " t > b ", the voltage  $\upsilon_c$  of capacitor decreases (*due to oscillation of source voltage*). This means that the "+" charge starts to flow back from the capacitor into the source and the *current direction is inverted* (negative values of current in graph).

- So that one can use similar mathematical expression as in case of DC current, one has introduced the

# reactance of a capacitor

$$X_C = \frac{1}{\omega C} \tag{23}$$

With this definition, the relation (21) can be rewritten as

$$\nu_{0C} = i_0 X_C \tag{24}$$

As 
$$i_0 = \frac{1}{0.707} * I_and_v_0 = \frac{1}{0.707} * V$$
 from (24) one gets  $V_C = IX_C$  (25)

Note that " $X_C$ " in (24) relates the *maximum* values while in (25) it relates the *rms* (*effective*) values of *current in circuit* and *difference of potential on capacitor plates*.

- The expressions (24, 25) can be considered as applications of Ohm's law in AC circuit for an "element with resistance = reactance  $X_c$ ". The reactance produces an infinite resistance for DC current because for f = 0,  $\omega = 0$  one gets  $X_C \sim (1/\omega = 1/0) = \infty$ . In a DC circuit, after getting fully charged, a capacitor interrupts the current through wires connected at its terminals. In a AC circuit its "resistance" becomes negligible for very high frequencies because  $X_C \sim (1/\omega) = (1/\infty) \cong 0$ ; i.e. it acts as a "short circuit". The increase of C-value decreases the reactance or the effective resistance in circuit because  $X_C \sim (1/C)$ .

## K.Angoni, Physics Dept., Vanier College 13.4 INDUCTOR IN AC CIRCUIT

- The scheme in fig.7 shows an inductor L *in series* to an *AC source*. Let's consider a moment when the *current* "i" is *increasing* and it is directed as shown. The inducted *emf* ( $\varepsilon_L = v_L$  *i.e.* L-voltage) builds up an induced current in opposite direction to "i" in fig. By applying the second Kirchhoff rule for the circuit

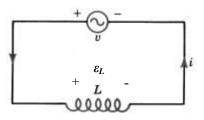


Figure 7

one gets 
$$v - v_L = 0$$
 (26)

The magnitude of potential difference at inductor's terminals is

$$v_L = \varepsilon_L = L \frac{di}{dt} \tag{27}$$

Relations (26, 27) define completely (magnitude and direction) the potential difference at inductor terminals. In the following we refer

to the voltage  $v_L$  (27) at inductor terminals instead of  $\varepsilon_L = -L \frac{di}{dt}$  which negative sign is transferred in front of voltage  $v_L$  at relation (26).

- As the current in circuit at any moment is given by expression  $i = i_0 \sin(\omega t)$  (28)

$$\frac{di}{dt} = i_0 \omega \cos(\omega t) - and - \upsilon_L = Li_0 \omega \cos(\omega t). \text{ So, voltage at inductor is} \qquad \upsilon_L = \upsilon_{0L} \cos(\omega t) \tag{29}$$

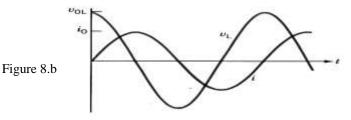
where 
$$v_{0L} = i_0 \omega L \tag{30}$$

Finally, one rewrites (29) in form 
$$v_L = v_{0L} \cos(\omega t) = v_{0L} \sin(\omega t + \pi/2) \quad (31)$$

The *phasors* in figure 8.a and the graphs of expressions (28,31) in figure 8.b show that the *voltage phasor at inductor* terminals *leads* the *current* phasor into the inductor  $by \pi/2$  radians.



1 iguile



- To use the Ohm's law for an inductor in AC circuits, one has introduced the parameter  $X_L = \omega L$  (32) This parameter is known as the *reactance* and it measures the *resistance* of *ideal inductor* in AC circuits. Then, the relation (30) for max. values can be rewritten as  $v_{0L} = i_0 X_L$  (33)

After multiplying both sides by 0.707, one gets 
$$V_L = I_L X_L$$
 (34)

The relations (33,34) relate the *amplitudes* and *rms* values of voltage and current for an ideal inductor.

- The relation (32) shows that, in contrary to capacitor, the resistance of an ideal inductor in an AC circuit (*i.e. the reactance*) increases *with frequency* increase. An *ideal inductor* would allow passing a DC current with *zero resistance* but it does present "*resistance*" to AC current. This "resistance" increases with the increase of frequency and the increase of its inductance (i.e. L-value).

In AC circuits: - the Ohms law does apply only for max. values and rms values of current and voltage but it is *not valid for instantaneous values*.

- the resistance of a resistor "R" does not depend on frequency.
- the reactance of a capacitor "  $X_C = 1 / \omega C$ " decreases with frequency increase.
- the reactance of an inductor "  $X_L = \omega L$ " increases with frequency increase.